

Priors comparison in Bayesian mediation framework with binary outcome

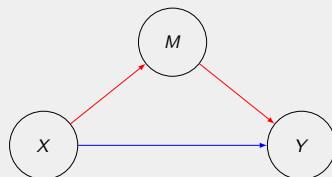
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Mediation

- outcome variable Y .
- exposure variable X .
- mediator variable M .



- The purpose is to decompose the causal effect of X on Y into two parts
 - The effect that passes through the mediator M (\rightsquigarrow indirect effect)
 - The effect that does not (\rightsquigarrow direct effect).

Motivation of my works

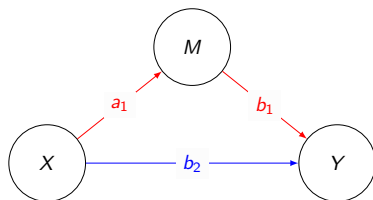
- Practical issues in psychology.
- Propose alternative statistical solutions: \rightsquigarrow Bayesian framework

Gaussian model: case of correlation

- The most widely model to evaluate the effect of X on Y is the linear regression:

$$Y = \psi_0 + \psi X + \varepsilon, \quad \varepsilon \sim \mathcal{N}(0, \sigma^2)$$

- ψ measures the association between X and Y .



In presence of the mediator M ,

- the linear model is of the form:

$$\begin{aligned} Y &= b_0 + b_1 M + b_2 X + \varepsilon_2 \\ M &= a_0 + a_1 X + \varepsilon_1 \end{aligned} \quad \implies \quad Y = b_0 + b_1 a_0 + (a_1 b_1 + b_2) X + a_1 \varepsilon_1 + \varepsilon_2$$

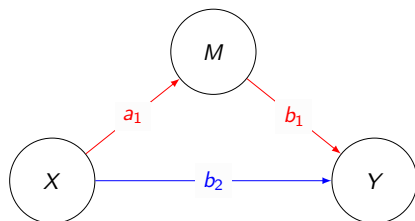
where $\varepsilon_i \sim \mathcal{N}(0, \sigma_i^2)$, $i = 1, 2$.

- The total effect is

$$\psi = \underbrace{b_2}_{\text{Direct}} + \underbrace{a_1 b_1}_{\text{Indirect}} .$$

Mediation with binary outcome

- outcome variable $Y \in \{0, 1\}$.
- exposure variable X .
- mediator variable $M \in \mathcal{M} \subset \mathbb{R}$.



$$\begin{cases} \mathbb{E}(Y|X, M) = \frac{1}{1 + e^{-(b_0 + b_1 M + b_2 X)}} \\ M = a_0 + a_1 X + \varepsilon, \quad \varepsilon \sim \mathcal{N}(0, \sigma^2 I) \end{cases}$$

Problem: Decomposition of the effect of X on Y in the logistic case.

The decomposition of the total effect is not valid for logistic mediation model.

- ψ measures the total effect

$$\mathbb{E}(Y|X) = \frac{1}{1 + e^{-(\psi_0 + \psi X)}} \quad (*)$$

- b_2 measures the direct effect

$$\mathbb{E}(Y|X, M) = \frac{1}{1 + e^{-(b_0 + b_1 M + b_2 X)}} \quad (**)$$

But

$$\psi \neq b_2 + a_1 b_1$$

If we replace M by $M = a_0 + a_1 X + \varepsilon$ in (**), we do not obtain (*)

Causal Effect

- We want to define the causal effect of the exposure $X \in \{0, 1\}$ on the outcome Y .
- Y_x is the potential outcome if $X = x$, $x \in \{0, 1\}$.
- The average causal effect of X on Y is

$$ACE = \mathbb{E}(Y_1 - Y_0)$$

Theorem

Assume that

- 1 consistency assumption

if $X = x$, then $Y_x = Y$,

- 2 ignorability assumption,

$Y_x \perp\!\!\!\perp X$ for $x \in \{0, 1\}$,

We have

$$ACE = \mathbb{E}(Y|X = 1) - \mathbb{E}(Y|X = 0)$$

In presence of a mediator Pearl (2001)

- 1 Direct effect is the difference between the potential outcomes Y_1 and Y_0 but imagining that the mediator is blocked at its value M_x

- 1 Pure Natural Direct Effect when $x = 0$,

$$NDE(0) = \mathbb{E}(Y_{1,M_0} - Y_{0,M_0})$$

- 2 Total Natural Direct Effect, when $x = 1$,

$$NDE(1) = \mathbb{E}(Y_{1,M_1} - Y_{0,M_1})$$

- 2 Indirect effect is the difference between the potential outcome Y_x but imagining that the mediator corresponds to M_1 and to M_0

- 1 Pure Natural Indirect Effect when $x = 0$,

$$NIE(0) = \mathbb{E}(Y_{0,M_1} - Y_{0,M_0})$$

- 2 Total Natural Indirect Effect, when $x = 1$,

$$NIE(1) = \mathbb{E}(Y_{1,M_1} - Y_{1,M_0})$$

A simple calculation provides

$$ACE = PNDE + TNIE = PNIE + TNDE$$

Identifiability of NDE and NIE

- The potential outcome $Y_{x, M_{x^*}}$ is never observed since $x \neq x^*$.
- Additional assumptions are required to obtain the identifiability of the effects (see for instance Pearl, 2001; Imai et al., 2010).
- Under these, we have, for $x, x^* \in \{0, 1\}$,

$$\mathbb{E}(Y_{x, M_{x^*}}) = \int_{-\infty}^{+\infty} \mathbb{E}(Y|X = x, M = m) f_{M|X=x^*}(m) dm$$

⇨

$$NDE(x) = \int [\mathbb{E}(Y|X = 1, M = m) - \mathbb{E}(Y|X = 0, M = m)] d\mathbb{P}_{M|X=x}(m)$$

$$NIE(x) = \int \mathbb{E}(Y|X = x, M = m) d\mathbb{P}_{M|X=1}(m) - \int \mathbb{E}(Y|X = x, M = m) d\mathbb{P}_{M|X=0}(m)$$

Gaussian example:

$$NDE(0) = NDE(1) = b_2, \quad NIE(0) = NIE(1) = a_1 b_1.$$

Bayesian inference of effects NDE(x) et NIE(x)

$$\begin{cases} M = a_0 + a_1 X + \varepsilon & \alpha = (a_0, a_1) \\ \mathbb{E}(Y|X, M) = \frac{1}{1 + e^{-(b_0 + b_1 M + b_2 X)}} & \beta = (b_0, b_1, b_2) \end{cases}$$

- Likelihood function :

$$f(Y, M|\alpha, \beta, \sigma^2, X) = \Phi_1(Y|\beta, M, X)\Phi_2(M|\alpha, \sigma^2, X)$$

$$\text{where } \begin{cases} \Phi_1(Y|\beta, M, X) = \frac{\exp(Y(b_0 + b_1 M + b_2 X))}{1 + \exp(b_0 + b_1 M + B_2 X)} \\ \Phi_2 \text{ Gaussian } \mathcal{N}(a_0 + a_1 X, \sigma^2 I_n) \end{cases}$$

- prior distribution of α, β, σ^2 .
- parameters of Interest:

$$\begin{aligned} \text{NDE}_\theta(x) &= \frac{1}{\sigma\sqrt{2\pi}} \int \left[\frac{1}{1 + e^{-(\beta_0 + \beta_1 m + \beta_2)}} - \frac{1}{1 + e^{-(\beta_0 + \beta_1 m)}} \right] e^{-\frac{1}{2\sigma^2}(m - \alpha_0 - \alpha_1 x)^2} dm \\ \text{NIE}_\theta(x) &= \frac{1}{\sigma\sqrt{2\pi}} \int \frac{1}{1 + e^{-(\beta_0 + \beta_1 m + \beta_2 x)}} \left[e^{-\frac{1}{2\sigma^2}(m - \alpha_0 - \alpha_1)^2} - e^{-\frac{1}{2\sigma^2}(m - \alpha_0)^2} \right] dm. \end{aligned}$$

↪ Non-explicit function of θ

Construction of the prior

We propose strategies with different degrees of information :

- a weakly G-prior introduced by Zellner (1971).
- an informative prior resulting from Launay et al. (2015)
transfer Learning

		linear regression	Logistic regression	
		σ^2	α	β
G-prior	weakly info.	$\frac{1}{\sigma^2} \mathbf{1}_{\mathbb{R}^+}$	G-prior	
Informative	info.		Launay et al. (2015)	

- For linear regression model (Zellner, 1971)

$$Y = \mathbf{X}\beta + \varepsilon, \quad \varepsilon \sim \mathcal{N}(0, \sigma^2 I_n), \quad \mathbf{X} = [\mathbf{1}, X_1, \dots, X_p].$$

G-prior is define as follows

$$\begin{cases} \beta | \sigma^2, \mathbf{X} \sim \mathcal{N}_{p+1}(\tilde{\beta}, g\sigma^2(\mathbf{X}'\mathbf{X})^{-1}) \\ \pi(\sigma^2 | \mathbf{X}) \propto \sigma^{-2} \end{cases}$$

↪ The choice $\tilde{\beta} = 0$ and $g = n$ gives to prior information the same weight as an observation.

- Generalisation to logistic regression (Marin and Robert, 2007)

$$\beta | \mathbf{X} \sim \mathcal{N}_{p+1}(\tilde{\beta}, g(\mathbf{X}'W\mathbf{X})^{-1}), \quad W = \text{diag}(p_i(1 - p_i)).$$

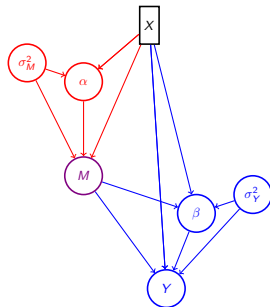
↪ The choice $\tilde{\beta} = 0$ and $p_i = 1/2$ gives a weak information to the prior.

G-priors and mediation model

- Decomposition of the joint distribution :

$$f(M, Y, \alpha, \sigma^2, \beta | X) = \Phi_1(Y | \beta, \sigma_Y^2, X, M) \pi(\beta, \sigma_Y^2 | X, M) \\ \Phi_2(M | \alpha, \sigma_M^2, X) \pi(\alpha, \sigma^2 | X).$$

- $\pi(\beta | X, M)$ G-prior logistic regression
 $\mathbb{E}(Y | X, M) = \frac{1}{1 + e^{-(b_0 + b_1 M + b_2 X)}}$
- $\pi(\alpha, \sigma^2 | X)$ G-prior linear regression
 $M = a_0 + a_1 X + \varepsilon_M.$



Remark on the Gaussian mediation model

- Galharret and Philippe (2021) use the same strategy for the Gaussian mediation model.
- Nuijten et al. (2015) address this problem as two independent Gaussian regression models.

Proposition

In the mediation model we have:

$$\text{NDE}(0) = 0 \iff \text{NDE}(1) = 0 \iff b_2 = 0$$

$$\text{NIE}(0) = 0 \iff \text{NIE}(1) = 0 \iff a_1 b_1 = 0$$

Test for direct effect ($b_2 = 0$) the likelihood ratio test

Test for indirect effect ($a_1 b_1 = 0$) bootstrap is used to approximate confidence interval for $a_1 b_1 \rightsquigarrow$ the performances are not very good for small samples.

Test for the indirect effect :

$$\mathcal{H}_0 : \text{NIE}_\theta(x) = 0 \text{ against } \mathcal{H}_1 : \text{NIE}_\theta(x) \neq 0.$$

Decision rule : let \mathcal{I}_α be the credible interval of $\text{NIE}_\theta(x)$

$$P(\text{NIE}_\theta(x) \in \mathcal{I}_\alpha | Y, M) = 1 - \alpha$$

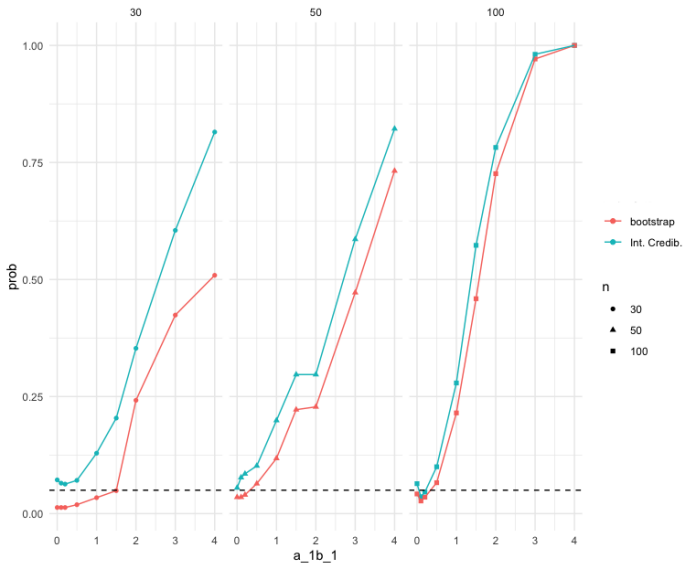
$0 \notin \mathcal{I}_\alpha \rightsquigarrow$ The absence of indirect effect is rejected

Remark

- According to Bernstein von Mises theorem, for all $\theta \in \Theta$ such as $a_1 b_1 = 0$, the frequentist probability satisfies

$$P_\theta(0 \in \mathcal{I}_\alpha) \rightarrow \alpha$$

Numerical results for indirect effect



$a_1 b_1 = 0$ gives the empirical level

Informative model M_1 (Launay et al., 2015)

We assume that

- 1 A historical data are available \mathcal{D}_h and
- 2 A Bayesian analysis has been done on \mathcal{D}_h

$$m_h = \mathbb{E}(\alpha_h, \beta_h | \mathcal{D}_h)$$

$$\Sigma_h = \text{Var}(\alpha_h, \beta_h | \mathcal{D}_h)$$

Application: longitudinal study: historical data come from the previous time step.

Assumption: Only small changes in parameters between the two studies.

Prior distribution of (α, β) :

$$(\alpha, \beta) \sim \mathcal{N}_5(K m_h, g \Sigma_h)$$

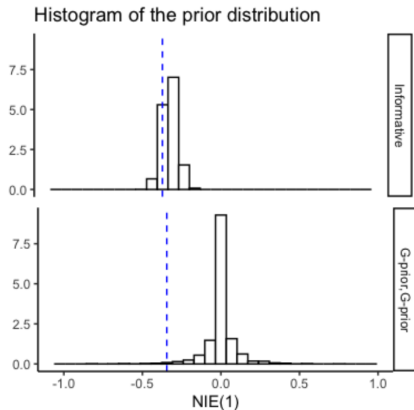
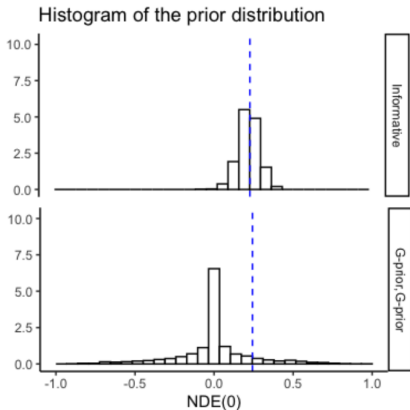
where $K = \begin{pmatrix} k_1 & & \\ & \ddots & \\ & & k_J \end{pmatrix}$ et k_1, \dots, k_J are i.i.d. $k_j \sim \mathcal{N}(1, \tau^2)$.

$\rightsquigarrow g$ et τ^2 hyperparameters of the model.

Historical data : $n_h = 100$, $\alpha_h = (1, -2)$ et $\beta_h = (-0.5, 1.5, 1)$.

data : We simulate samples with the following parameters

	α	β	NDE(0)	NIE(1)
Case 1	(1, -2)	(-0.5, 1, 1.5)	0.24	-0.35
Case 2	(1, -1)	(-1, 2, 0.5)	0.07	-0.29
Case 3	(1, 1)	(1, 1, -1)	-0.15	0.15



Numerical results

N	model	NDE(0)=PNDE				NIE(1)=TNIE			
		bias	RMSE	coverage	length	bias	RMSE	coverage	length
CASE 1: Time-invariant parameters									
30	<i>info</i>	0.01	0.11	0.97	0.48	0.01	0.11	0.96	0.43
30	<i>G-prior</i>	-0.02	0.16	0.96	0.63	0.04	0.12	0.95	0.48
50	<i>info</i>	0.00	0.09	0.96	0.40	0.01	0.08	0.96	0.34
50	<i>G-prior</i>	-0.01	0.12	0.95	0.49	0.02	0.09	0.96	0.37
100	<i>info</i>	0.00	0.07	0.96	0.30	0.01	0.06	0.96	0.24
100	<i>G-prior</i>	0.00	0.07	0.96	0.30	0.01	0.06	0.96	0.24
CASE 2: Time-varying parameters with invariance of the sign of the effects									
30	<i>info</i>	0.03	0.09	0.97	0.39	0.02	0.10	0.96	0.40
30	<i>G-prior</i>	0.00	0.13	0.93	0.50	0.02	0.11	0.96	0.43
50	<i>info</i>	0.02	0.07	0.97	0.32	0.01	0.08	0.96	0.33
50	<i>G-prior</i>	0.00	0.10	0.94	0.40	0.02	0.08	0.96	0.34
100	<i>info</i>	0.00	0.06	0.98	0.24	0.01	0.06	0.94	0.24
100	<i>G-prior</i>	-0.01	0.07	0.96	0.28	0.01	0.06	0.95	0.24
CASE 3: Time-varying parameters with changing sign of the effects									
30	<i>info</i>	0.04	0.16	0.94	0.59	-0.04	0.10	0.92	0.36
30	<i>G-prior</i>	0.00	0.16	0.95	0.60	-0.01	0.10	0.95	0.39
50	<i>info</i>	0.03	0.13	0.94	0.48	-0.03	0.08	0.94	0.29
50	<i>G-prior</i>	0.00	0.14	0.94	0.49	-0.01	0.08	0.95	0.3
100	<i>info</i>	0.00	0.07	0.96	0.30	0.01	0.06	0.96	0.24
100	<i>G-prior</i>	0.00	0.07	0.96	0.30	0.01	0.06	0.96	0.24

Application in psychology

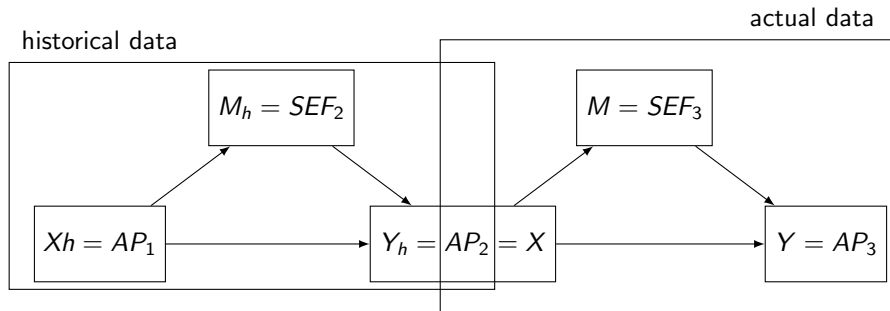
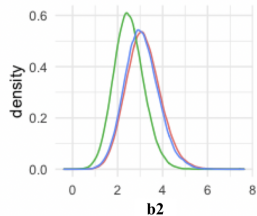
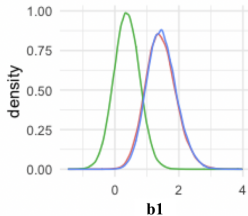
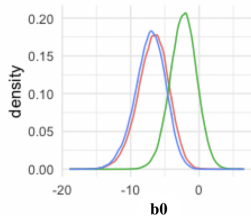
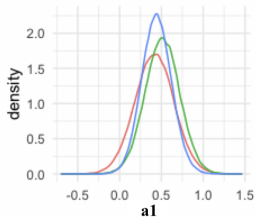
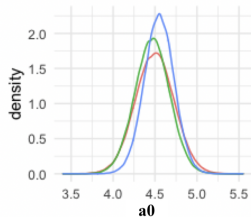


Figure: Structural model. *AP*: Academic Performance, *SEF*: Self Efficacy Feeling.

Estimation of the regression coefficients



Estimation of the effects

	<i>G-prior</i>			<i>info</i>		
	Estimate	Lower	Upper	Estimate	Lower	Upper
PNIE	0.094	-0.014	0.211	0.114	0.016	0.222
TNIE	0.056	-0.011	0.140	0.058	0.003	0.128
PNDE	0.473	0.277	0.664	0.497	0.296	0.696
TNDE	0.434	0.245	0.634	0.441	0.241	0.646

Table: 95 %-Credible Interval for the effects at the second time measurement

- 1 Bayesian estimation of the direct and indirect effects:
the posterior distribution of both effects can be calculated
- 2 Procedure to include information coming from historical study
Improvement of the precision and the accuracy
- 3 Testing procedure for the effects
Improvement of the significance level and the power comparing to bootstrap approximation

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